

TELE-IMMERSIVE VIRTUAL ENVIRONMENTS FOR COLLABORATIVE KNOWLEDGE DISCOVERY

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Keywords: Virtual Reality, Tele-Immersion, Interactive Systems, Environmental Data

ABSTRACT

This paper describes the design and implementation of two tele-immersive applications, CVD and Cave6D, both designed to support collaborative knowledge discovery from large multidimensional datasets. CVD integrates the capabilities of two existing VR applications, Cave5D and Virtual Director, in order to provide immersive experiences of distributed data using high performance networks and interactive hardware and software. Cave6D is similar in function yet is tightly integrated with the CAVERNSoft toolkit so as to provide access to remote computational platforms and databases.

INTRODUCTION

In recent years there has been a rapid increase in the capability of environmental observation and modeling systems to provide high resolution spatial and temporal data about the world around us. It is not enough, however, to be able to collect, generate or share large amounts of data. Scientists, educators, students and managers must have the ability to collaboratively view, analyze and interact with the data in a way that is understandable, repeatable and intuitive.

Concurrent advances in visualization and computational capabilities have spurred the creation and use of realistic, three-dimensional virtual environments for interaction with and analysis of this data. Viewing and interacting with these large multivariate datasets in a geo-

referenced virtual environment provides an actual sense of presence that inherently changes the way the data is analyzed (Wheless *et al.*, 1995) thereby aiding in the mental process of assimilating complex information. Users are able to navigate through, view and interact with the data in a fully three-dimensional context, thus preserving necessary geospatial relationships crucial for intuitive analysis.

High performance networks, such as the NSF-funded very High Bandwidth Network Service (vBNS), now provide an infrastructure for low latency multi-user access to these virtual environments (DeFanti *et al.*, 1996). The use of these Collaborative Virtual Environments (CVEs) enable users at many distributed sites to interact with each other and with the data in a many-to-many session from within a common virtual world. Linking remote users into a shared virtual space enables a high level mode of collaboration that is conducive to knowledge discovery (NSTC, 1998).

We describe in this paper our efforts to integrate this collaborative capability into an existing VR-based scientific visualization application, Cave5D (Wheless *et al.*, 1996). Our objective is to enable multi-user immersive visualization of large multi-dimensional datasets in support of oceanographic, atmospheric and terrestrial scientific studies. Two separate implementation paths were followed, each resulting in a distinct prototype. In one case, Cave5D was augmented with remote interaction techniques and camera choreography capabilities provided by the VR application Virtual Director. In the other case, Cave5D was retrofitted with collaborative features provided by the CAVERNSoft toolkit (Leigh *et al.*, 1997), a software library that is designed to allow for easy development of similar applications.

TELE-IMMERSION

We use the concept of *Tele-Immersion* as the fundamental underpinnings of our work. We define tele-immersion as the union of audio and video conferencing, networked collaborative VR and image-based modeling in the context of significant computing and data mining. Tele-immersion enables users in different locations to collaborate in a shared, virtual, or simulated environment as if they are in the same room. It is the ultimate synthesis of networking and media technologies to enhance CVEs.

The development of tele-immersive CVEs is currently one of the most challenging areas of research in Virtual Reality (VR) because new dimensions to human-factors, networking, and database issues must be

explored. For example, human-factors research in VR has traditionally focused on the development of natural interfaces for manipulating virtual objects and traversing virtual landscapes. Collaborative manipulation, on the other hand, requires the consideration of how participants should interact with each other in a shared space, in addition to how co-manipulated objects should behave. Other issues include: how participants should be represented in the collaborative environment; how to effectively transmit non-verbal cues that real-world collaborators so casually and effectively use; how to best transmit video and audio via a channel that allows both public addressing as well as private conversations to occur; and how to sustain a virtual environment even when all its participants have left. Many of these issues were explored in our development work.

Although there are a broad range of devices that support tele-immersion activities, our work focuses on projection-based graphical devices such as the Immersadesk or CAVE™ (Cruz-Neira *et al.*, 1993). Growing in number since 1992 from just a few at selected research institutions, the number of Immersadesks, CAVEs™ and CAVE-like devices now number well into the hundreds. Stereographic LCD shutter glasses and head/hand tracking is often used to augment the experience. The CAVELibrary software API (please see <http://www.ncsa.uiuc.edu/VR/cavernus/>) is an example of a common underlying interface between CAVE-specific applications, serving to coordinate all ancillary devices (eg: LCD glasses, navigational wand), stereo transformations and program synchronization.

The Immersadesk, a drafting-table format, projection-based device with a single 4' by 5' angled screen, enables users to view and interact with a CVE in a semi-immersive fashion. This type of semi-immersive VR is useful for applications that do not require full immersion of the user into the virtual environment, such as a 3D model of a bio-molecular simulation. However, full immersion is more useful for realistic portrayal and useful interaction in very large-scale virtual environments that also include small man-made objects and fine-scale environmental features.

The CAVE™ allows for such a full immersion. The CAVE™ is a 10x10x10-foot structure consisting of rear-projected screen walls and a front-projected floor. Images appear to float in space, with the user free to "walk" around them, yet maintain a proper perspective. This information can be much richer and more accurate, with finer granularity of many more variables, and with sound as well as visual depictions.

TELE-IMMERSIVE APPLICATIONS

Linking these VR devices together in dedicated tele-immersive environments is an area of active research. Tele-immersive applications not only combine audio, video, virtual worlds, simulations, and many other complex technologies, but they also require huge bandwidth, very fast responses, and guarantees of delivery. We now describe two tele-immersive applications, CVD and Cave6D, both stemming from one of the first VR applications for interaction with large datasets in the CAVETM, Cave5D.

Cave5D

Cave5D is a configurable VR application framework that integrates the CAVELibrary VR software API with the Vis5D visualization API (Hibbard *et al.*, 1992) in order to visualize large multivariate data sets in the CAVE or on the ImmersaDesk and to enable user interaction with the data.

The representation of data within a virtual world involves three primary steps: the conversion of data into a graphical objects, the mapping of the graphical objects into the physical space of the virtual world, and defining interactions with the graphical objects (and thus, by association, with the data). Cave5D performs these functions in addition to managing the data sets, displaying the graphical objects, and specifying the space-time definition of the virtual environment.

Large multi-dimensional numerical data sets from atmospheric, oceanographic, and other similar models, are visualized in Cave5D using isosurfaces, contour slices, volume visualization, wind/trajectory vectors, and various image projection formats. Users are able to navigate through the data, change the view of the entire data volume and interactively slice through the data set of interest while within the virtual environment. Navigation of a data set, as defined here, is the steering of the VR user's view through the graphical display of multi-dimensional data.

Virtual Director

Managing and documenting visualizations from large scientific datasets can be an unwieldy and difficult task. When attempting to spatially navigate and temporally record a large-scale data set, time and space become non-trivial to the VR applications manager. The tracking of simulation time (runtime, interpolated, or non-linear), real clock time, VR display/recording/playback time, and digital frame time, is a fundamental problem in the design of a general navigation and recording system for VR scientific applications. A simulation often

produces large data sets that are stored, and then post-processed and visualized with interactive VR visualization packages. To add to this complexity is the effort to convert

more personalization. The use of multicast audio with the

CAVERN-based client and server applications. An IRB is an autonomous repository of persistent data driven by a database and accessible by a variety of networking interfaces in order to provide a tightly coupled mechanism to automatically transfer messages. Combining the distributed shared memory model with active database technology and real-time networking technology, this hybrid system allows the rapid construction of arbitrary topologies of interconnected, tele-immersed participants.

CAVERNSoft has the added ability of supporting the feature of *persistence*. That is, even when all the participants have left the environment and the virtual display devices have been switched off, the environment continues to evolve. This evolution would be caused either

freely available *vat* application permits verbal communication among all CVE users. Techniques have been developed to share CVD current status information and camera spline path information so that users at remote sites can navigate and control the virtual camera.

The power of Cave5D using Vis5D graphical display techniques in the immersive environment of the CAVE or Immersadesk has thus been greatly leveraged by the functionality of Virtual Director. Animations and images of temporally varying behaviors in several different environmental datasets made from Cave5D/Virtual Director may be viewed at <http://www.ncsa.uiuc.edu/VR/grants/virdir>. CVD has been demonstrated several times, most recently at Supercomputing'98 in Orlando, FL. (Wheless *et al.*, 1998b) in which several users spread over thousands of miles were able to interact in a shared virtual environment.

CAVERNSoft And Tele-Immersion

Naturally, tele-immersive CVEs pose new challenges as they require an unconventionally broad range of networking, database and graphics capabilities. This vast range makes the rapid construction of complex CVEs difficult. Most attempts at building networking and database architectures for CVEs have resulted in ad-hoc solutions that are specifically designed to solve a small range of problems. The CAVERNSoft programming environment was designed to provide a systematic solution to these challenges (Leigh *et al.*, 1997).

The CAVERNSoft framework employs an Information Request Broker (IRB) as the nucleus of all

temporally varying fields are viewed synchronously. This constraint forces a shared field of reference on all participants even with all other variables locally selectable.

Cave6D has been demonstrated at several venues, including the 1998 Next Generation Internet meeting held in Washington, DC, the 1998 Internet2 Spring Members meeting, and at Supercomputing 1998 as part of the iGrid project.

CONCLUSIONS

We have described our work developing and using two tele-immersive applications for knowledge discovery with large multivariate datasets. These applications allow raw data to become usable information and then cognitively useful knowledge for multiple users in many locations. The design of these collaborative applications incorporates multiple data streams from archived data stores, model results and advanced instrumentation. Re-architecting both applications to more closely merge capabilities is in progress.

Clearly, the near real-time feedback provided by such collaborative applications have the potential to change the way data or model results are viewed and interpreted, the resulting information disseminated and the ensuing decisions or policies enacted.

ACKNOWLEDGEMENTS

The development of Cave5D is supported by a grant from the NSF New Technologies program (ASC-9634151). The vBNS connection to Old Dominion University is made possible by NSF grant NCR-9613910. This work is a result of research sponsored in part by NOAA Office of Sea Grant, U.S. Department of Commerce, under Grant No. NA56RG0489 to the Virginia Graduate Marine Science Consortium and the Virginia Sea Grant College Program. The U.S. Government is authorized to produce and distribute research reprints for governmental purposes notwithstanding any copyright notification that may appear hereon. The virtual reality research, collaborations, and outreach programs at EVL are made possible through major funding from the National Science Foundation, the Defense Advanced Research Projects Agency, and the US Department of Energy; specifically NSF awards CDA-9303433, CDA-9512272, NCR-9712283, CDA-9720351, and the NSF ASC Partnerships for Advanced Computational Infrastructure program.

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